

Math 2233 - Lecture 10: Reduction of Order

Agenda

1. Solutions of 2nd Order, Homogeneous, Linear ODEs
 - ▶ E&U Theorem
 - ▶ Superposition Principle
 - ▶ Completeness Theorem
2. The Wronskian Condition and Linear Algebra
3. Reduction of Order
4. Examples
5. Constant Coefficients Case

2nd Order Homogeneous, Linear ODEs

Most General 2nd Order Linear ODE

$$a(x)y'' + b(x)y' + c(x)y = d(x)$$

2nd Order, Linear ODEs : Standard Form

$$y'' + p(x)y' + q(x)y = g(x)$$

Homogeneous 2nd Order, Linear ODEs : Standard Form

$$y'' + q(x)y' + p(x)y = 0$$

Fundamental Theorems

Theorem (Existence and Uniqueness Theorem)

*So long as the functions $p(x)$, $q(x)$, and $g(x)$ are continuous, there exists **one and only one** solution of*

$$y'' + p(x)y' + q(x)y = g(x) \quad (1)$$

satisfying

$$\begin{aligned} y(x_0) &= y_0 \\ y'(x_0) &= y'_0 \end{aligned} \quad (2)$$

The Superposition Principle

Theorem (Superposition Principle)

If $y_1(x)$ and $y_2(x)$ are two solutions of

$$y'' + p(x)y' + q(x)y = 0 \quad (3)$$

then any function of the form

$$y(x) = c_1 y_1(x) + c_2 y_2(x) \quad (4)$$

will also be a solution of (3).

The Completeness Theorem

Theorem (Completeness Theorem)

If $y_1(x)$ and $y_2(x)$ are two solutions of

$$y'' + p(x)y' + q(x)y = 0 \quad (3)$$

such that

$$0 \neq W[y_1, y_2](x) \equiv y_1(x)y_2'(x) - y_1'(x)y_2(x) \quad (5)$$

*Then **every solution** of (3) can be written as*

$$y(x) = c_1 y_1(x) + c_2 y_2(x) \quad (6)$$

(5) is called the **Wronskian Condition**.

(6) is thus **the form of the general solution** to (3).

Solutions y_1, y_2 satisfying (5) are called a **fundamental set of solutions** (or **independent solutions**) of (3).

Geometric Interpretation of the Wronskian Condition

Digression: Independent Vectors in the Plane

Two non-zero vectors $\mathbf{A}, \mathbf{B} \in \mathbb{R}^2$ are said to be **independent** if

$$\mathbf{B} \neq \lambda \mathbf{A}$$

(i.e., \mathbf{A} and \mathbf{B} are neither parallel or anti-parallel).

Fact

*If $\mathbf{A}, \mathbf{B} \in \mathbb{R}^2$ are independent vectors, then **every** vector $\mathbf{V} \in \mathbb{R}^2$ can be expressed as*

$$\mathbf{V} = c_1 \mathbf{A} + c_2 \mathbf{B}$$

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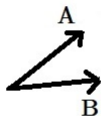
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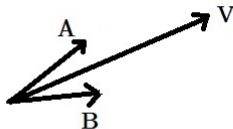
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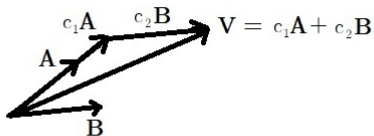
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Connection with the Wronskian Condition

Now recall the Wronskian Condition

$$0 \neq W[y_1, y_2](x) = y_1(x)y_2'(x) - y_1'(x)y_2(x)$$

Suppose this condition **does not hold** for two functions $y_1(x)$ and $y_2(x)$; i.e.,

$$y_1(x)y_2'(x) - y_1'(x)y_2(x) = 0 \quad (5)$$

Then we can think of (5) as a differential equation for $y_2(x)$ (with $y_1(x)$ a given function). After dividing (5) by $y_1(x)$

$$y_2' - \frac{y_1'(x)}{y_1(x)}y_2 = 0$$

This is a first order linear ODE in the standard form

$$y' + P(x)y' = G(x)$$

with $P(x) = \frac{y_1'(x)}{y_1(x)}$ and $G(x) = 0$. So we can readily solve it.

Connection with the Wronskian Condition, Cont'd

Noting that

$$\frac{d}{dx} (\ln |y_1(x)|) = \frac{1}{y_1(x)} y_1'(x) = -P(x)$$

$$\begin{aligned}\mu(x) &= \exp \left[\int P(x) dx \right] \\ &= \exp \left[- \int \frac{d}{dx} (\ln |y_1(x)|) dx \right] \\ &= \exp [-\ln |y_1(x)|] \\ &= \frac{1}{y_1(x)}\end{aligned}$$

and so

$$\begin{aligned}y_2(x) &= \frac{1}{\mu(x)} \int \mu(x) G(x) dx + \frac{C}{\mu(x)} \\ &= y_1(x) \int \frac{1}{y_1(x)} (0) dx + C y_1(x) \\ &= 0 + C y_1(x)\end{aligned}$$

Connection with the Wronskian Condition, Cont'd

We have just proved

Lemma

If $y_1(x)$ and $y_2(x)$ fail to satisfy the Wronskian condition, then

$$y_2(x) = \lambda y_1(x)$$

for some constant λ .

The analogy:

- ▶ Let \mathbf{A}, \mathbf{B} be vectors in the plane, so long as

$$\mathbf{B} \neq \lambda \mathbf{A}$$

every vector \mathbf{V} in the plane \mathbb{R}^2 can be expressed as

$$\mathbf{V} = c_1 \mathbf{A} + c_2 \mathbf{B}$$

- ▶ Let $y_1(x), y_2(x)$ be two solutions of

$$y'' + p(x)y' + q(x)y = 0 \quad (*)$$

If $y_1(x)$ and $y_2(x)$ satisfy the Wronskian Condition, then

$$y_2(x) \neq \lambda y_1(x)$$

and **every** solution of $(*)$ can be expressed as

$$y(x) = c_1 y_1(x) + c_2 y_2(x)$$

Reduction of Order

Recall that the general solution of a second order homogeneous linear differential equation

$$y'' + p(x)y' + q(x)y = 0 \quad (1)$$

is given by

$$y(x) = c_1 y_1(x) + c_2 y_2(x) \quad (2)$$

where y_1 and y_2 are any two solutions such that

$$0 \neq W[y_1, y_2](x) = y_1(x)y_2'(x) - y_1'(x)y_2(x) \quad (3)$$

I'll now show you how to find the general solution of (1) starting with just a single solution of (1).

Hypothesis:

Suppose we have one non-trivial solution $y_1(x)$ of (1) and suppose there is another solution of the form

$$y_2(x) = v(x)y_1(x) \quad .$$

(Here we are making an “ansatz” for a second solution.) Then

$$\begin{aligned} W[y_1, y_2] &= y_1 y_2' - y_1' y_2 \\ &= y_1(v' y_1 + v y_1') - y_1'(v y_1) \\ &= (y_1)^2 v' \\ &\neq 0 \end{aligned}$$

unless $v' = 0$.

Thus, any solution we construct by multiplying our given solution $y_1(x)$ by a non-constant function $v(x)$ will give us another linearly independent solution.

So let's look for a second solution indirectly, by finding a function $v(x)$ so that $v(x)y_1(x)$ is a solution.

Inserting $y(x) = v(x)y_1(x)$ into (1):

$$\begin{aligned} 0 &= \frac{d^2}{dx^2} (vy_1) + p(x) \frac{d}{dx} (vy_1) + q(vy_1) \\ &= v''y_1 + 2v'y_1' + vy_1'' + p(x)v'y_1 + p(x)vy_1' + qvy_1 \\ &= v(y_1'' + p(x)y_1' + q(x)y_1) + v''y_1 + (2y_1' + p(x)y_1) v' \end{aligned}$$

The first term vanishes since y_1 is a solution of (1), so $v(x)$ must satisfy

$$0 = y_1 v'' + (2y_1' + p(x)y_1) v' \quad (4)$$

or

$$v'' + \left(p(x) + \frac{2y_1'}{y_1} \right) v' = 0 \quad . \quad (5)$$

Note that this is a first order linear ODE for $v'(x)$.

So set

$$u(x) = v'(x) \quad . \quad (6)$$

Then (5) becomes

$$u' + \left(p(x) + \frac{2y_1'(x)}{y_1(x)} \right) u = 0 \quad . \quad (7)$$

The integrating factor for this 1st Order Linear ODE is

$$\begin{aligned} \mu(x) &= \exp \left[\int \left(p(x) + \frac{2y_1'(x)}{y_1(x)} \right) dx \right] \\ &= \exp \left[\int \frac{2y_1'(x)}{y_1(x)} \right] \exp \left[\int p(x) dx \right] \\ &= \exp \left[2 \int \left(\frac{d}{dx} (\ln |y_1(x)|) \right) dx \right] \exp \left[\int p(x) dx \right] \\ &= \exp [2 \ln [y_1(x)]] \exp \left[\int p(x) dx \right] \\ &= (y_1(x))^2 \exp \left[\int p(x) dx \right] \end{aligned}$$

And so

$$\begin{aligned} u(x) &= \frac{1}{\mu(x)} \int \mu(x) (0) dx + \frac{C}{\mu(x)} \\ &= 0 + C \frac{1}{(y_1(x))^2} \exp \left[- \int p(x) dx \right] \end{aligned}$$

and so

$$u(x) = \frac{C}{(y_1(x))^2} \exp \left[- \int^x p(t) dt \right] .$$

Now recall from (6) that $u(x)$ is the derivative of the factor $v(x)$ which we originally sought out to find. (recall $y_2(x) = v(x)y_1(x)$ will be our second solution)

So

$$\begin{aligned} v(x) &= \int^x u(t) dt + D \\ &= \int^x \left[\frac{C}{(y_1(t))^2} \exp \left[- \int^t p(t') dt' \right] \right] + D \end{aligned}$$

Since we only need one 2 second solution, we can take $C = 1$ and $D = 0$.

So given one solution $y_1(x)$ of (1), a second solution $y_2(x)$ of (1) can be formed by computing

$$v(x) = \int^x u(t) dt$$

where

$$u(x) = \frac{1}{(y_1(x))^2} \exp \left[- \int^x p(t) dt \right]$$

and then setting

$$y_2(x) = v(x)y_1(x) \quad .$$

The general solution of (1) is then

$$y(x) = c_1 y_1(x) + c_2 v(x) y_1(x) \quad .$$

This technique for constructing the general solution from single solution of a second order linear homogeneous differential equation is called **Reduction of Order**.

Summarizing

Theorem (Reduction of Order)

If $y_1(x)$ is a solution of

$$y'' + p(x)y' + q(x)y = 0 \quad (1)$$

then a 2nd independent solution $y_2(x)$ can be calculated via the formula

$$y_2(x) = y_1(x) \int \frac{1}{(y_1(s))^2} \exp \left[- \int^s p(t) dt \right] ds$$

Once y_2 has been calculated, the general solution to (1) can be written

$$y(x) = c_1 y_1(x) + c_2 y_2(x)$$

Example 1

$$y_1(x) = e^{-x}$$

is one solution of

$$y'' + 2y' + y = 0 \quad .$$

Find another linearly independent solution and then write down the general solution.

Well, $p(x) = 2$, so

$$\begin{aligned} u(x) &= \frac{1}{(y_1(x))^2} \exp \left[- \int^x p(t) dt \right] \\ &= \frac{1}{e^{-2x}} \exp [-2x] \\ &= e^{2x} e^{-2x} \\ &= 1 \end{aligned}$$

So

$$v(x) = \int^x u(t) dt = \int^x dt = x.$$

Example 1, Cont'd

Thus,

$$y_2(x) = v(x)y_1(x) = xe^{-x} \quad .$$

and so the general solution to the original ODE will be

$$y(x) = c_1 e^{-x} + c_2 x e^{-x}$$

Example 2

$$y_1(x) = x$$

is a solution of

$$x^2 y'' + 2xy' - 2y = 0 \quad .$$

This time we'll use the Reduction of Order formula

$$y_2(x) = y_1(x) \int \frac{1}{(y_1(x))^2} \exp \left[- \int p(x) dx \right] dx$$

(where I'm being a bit sloppy with respect to the variables of integration).

Putting the DE in standard form

$$y'' + \frac{2}{x} y' - \frac{2}{x^2} y = 0$$

we see

$$p(x) = \frac{2}{x} \quad , \quad q(x) = -\frac{2}{x^2}$$

We can now calculate a second solution

$$\begin{aligned}y_2(x) &= y_1(x) \int \frac{1}{(y_1(x))^2} \exp \left[- \int p(x) dx \right] dx \\&= x \int \frac{1}{x^2} \exp \left[- \int \frac{2}{x} dx \right] dx \\&= x \int \frac{1}{x^2} \exp [-2 \ln |x|] dx \\&= x \int \frac{1}{x^2} x^{-2} dx \\&= x \int x^{-4} dx \\&= x \left(-\frac{1}{3} x^{-3} \right) \\&= -\frac{1}{3} x^{-2}\end{aligned}$$

The general solution to the original differential equation is thus

$$\begin{aligned}y(x) &= c_1 y_1(x) + c_2 y_2(x) \\&= c_1 x + c_2 \left(-\frac{1}{3}x^{-2}\right) \\&= c_1 e^{-x} + c_2 x^{-2}\end{aligned}$$

In the last line, the constant factor of $-\frac{1}{3}$ has been “absorbed” into the arbitrary constant c_2 (for the sake of tidyness).

Second Order Linear Equations with Constant Coefficients

We are now ready to actually solve some linear ODE's of degree 2 **from scratch**.

We shall begin with differential equations of a particularly simple type; equations of the form

$$ay'' + by' + cy = 0 \quad (9)$$

where a , b and c are constants.

A clue as to how one might construct a solution to (9) comes from the observation that (9) implies that y'' , y' and y are related to one another by multiplicative constants.

But this is a property of exponential functions; i.e., a functions of the form

$$y(x) = e^{\lambda x} \quad (10)$$

have the property that

$$y' = \lambda e^{\lambda x} = \lambda y \quad \text{and} \quad y'' = \lambda^2 e^{\lambda x} = \lambda^2 y$$

We will therefore look for solutions of (9) having the form (10).

Constant Coefficients Case, Cont'd

Plugging (10) into (9) yields

$$0 = a\lambda^2 e^{\lambda x} + b\lambda e^{\lambda x} + ce^{\lambda x} = (a\lambda^2 + b\lambda + c) e^{\lambda x} \quad .$$

Since the exponential function $e^{\lambda x}$ never vanishes (for finite x) we must have

$$a\lambda^2 + b\lambda + c = 0 \quad .$$

Equation (11) is called the **characteristic equation** for (9). Any number λ satisfying the characteristic equation will give us a solution $y(x) = e^{\lambda x}$ of the original differential equation (9). Now because (11) is a quadratic equation we can employ the Quadratic Formula to find all of its roots:

$$a\lambda^2 + b\lambda + c = 0 \quad \Rightarrow \quad \lambda = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \quad .$$

However, a root λ of (11) need not be a real number.

We shall postpone until next week the case when the roots of (11) are complex numbers.

For simplicity, and just for today, we'll assume that $\sqrt{b^2 - 4ac}$ is a positive real number and so

$$\begin{aligned}\lambda_+ &= \frac{-b + \sqrt{b^2 - 4ac}}{2a} \\ \lambda_- &= \frac{-b - \sqrt{b^2 - 4ac}}{2a}\end{aligned}$$

are distinct real roots of (11). Thus,

$$\begin{aligned}y_1(x) &= e^{\lambda_+ x} \\ y_2(x) &= e^{\lambda_- x}\end{aligned}$$

will both be solutions of (9).

Note that

$$\begin{aligned}W[y_1, y_2](x) &= \left(e^{\lambda_+ x}\right) \left(e^{\lambda_- x}\right)' - \left(e^{\lambda_+ x}\right)' \left(e^{\lambda_- x}\right) \\ &= (\lambda_- - \lambda_+) e^{(\lambda_+ + \lambda_-)x} \\ &\neq 0\end{aligned}$$

Constant Coefficients Case, Cont'd

And so the solutions $y_1 = e^{\lambda_+ x}$ and $y_2 = e^{\lambda_- x}$ will form a fundamental set of solutions.

The general solution to

$$ay'' + by' + cy = 0 \quad (9)$$

will thus be

$$y(x) = c_1 e^{\lambda_+ x} + c_2 e^{\lambda_- x}$$

Method for Constant Coefficients Case

$$ay'' + by' + cy = 0 \quad (12)$$

1. Substitute “trial solution” $y(x) = e^{\lambda x}$ into (9).
2. Divide result by $e^{\lambda x}$ to get the **characteristic equation** for (9)

$$a\lambda^2 + b\lambda + c = 0 \quad (13)$$

3. Solve (13) either by factoring the LHS or via the Quadratic Formula

$$\lambda_+ = \frac{-b + \sqrt{b^2 - 4ac}}{2a}, \quad \lambda_- = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

4. So long as $b^2 - 4ac > 0$, the roots λ_+ and λ_- will be distinct real numbers, and the functions $y_1 = e^{\lambda_+ x}$ and $y_2 = e^{\lambda_- x}$ will form a fundamental set of solutions. The general solution will then be

$$y(x) = c_1 e^{\lambda_+ x} + c_2 e^{\lambda_- x}$$

What if $b^2 - 4ac \leq 0$?

- ▶ If $b^2 - 4ac = 0$, then
 $\lambda_+ = \lambda_- \Rightarrow y_1(x) = y_2(x) \Rightarrow$ only 1 independent solution

We need two independent solutions for to write down the general solution.

- ▶ If $b^2 - 4ac < 0$, then λ_{\pm} are complex numbers. What is $e^{\lambda x}$ when $\lambda \in \mathbb{C}$?

We'll resolve these two issues in the next lecture.

Example 3

$$y'' + 3y' + 2y = 0 \quad .$$

Setting $y(x) = e^{\lambda x}$ and plugging into the differential equation we get

$$\begin{aligned} 0 &= \lambda^2 e^{\lambda x} + 3\lambda e^{\lambda x} + 2e^{\lambda x} \\ &= e^{\lambda x} (\lambda^2 + 3\lambda + 2) \\ &= e^{\lambda x} (\lambda + 1)(\lambda + 2) \end{aligned}$$

Since $e^{\lambda x}$ never vanishes for any finite x , we must have

$$\lambda = -1 \quad \text{or} \quad \lambda = -2 \quad .$$

We thus find two distinct solutions

$$\begin{aligned} y_1(x) &= e^{-x} \\ y_2(x) &= e^{-2x} \quad . \end{aligned}$$

Example 3, Cont'd

Note that

$$\begin{aligned}W[y_1, y_2] &= (e^{-x}) \left(\frac{d}{dx} e^{-2x} \right) - \left(\frac{d}{dx} e^{-x} \right) (e^{-2x}) \\&= (e^{-x}) (-2e^{-2x}) - (-e^{-x}) (e^{-2x}) \\&= (-2 + 1) e^{-3x} \\&\neq 0\end{aligned}$$

and so $y_1(x) = e^{-x}$ and $y_2(x) = e^{-2x}$ are independent solutions.
The general solution is thus

$$y(x) = c_1 e^{-x} + c_2 e^{-2x} \quad .$$