

Math 2233 - Lecture 10: Reduction of Order

Agenda

1. Solutions of 2nd Order, Homogeneous, Linear ODEs
 - ▶ E&U Theorem
 - ▶ Superposition Principle
 - ▶ Completeness Theorem
2. The Wronskian Condition and Linear Algebra
3. Reduction of Order
4. Examples
5. Constant Coefficients Case

2nd Order Homogeneous, Linear ODEs

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Most General 2nd Order Linear ODE

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Homogeneous 2nd Order, Linear ODEs : Standard Form

$$y'' + q(x)y' + p(x)y = 0$$

Fundamental Theorems

Theorem (Existence and Uniqueness Theorem)

*So long as the functions $p(x)$, $q(x)$, and $g(x)$ are continuous, there exists **one and only one** solution of*

$$y'' + p(x)y' + q(x)y = g(x) \quad (1)$$

satisfying

$$\begin{aligned} y(x_0) &= y_0 \\ y'(x_0) &= y'_0 \end{aligned} \quad (2)$$

The Superposition Principle

Theorem (Superposition Principle)

If $y_1(x)$ and $y_2(x)$ are two solutions of

$$y'' + p(x)y' + q(x)y = 0 \quad (3)$$

then any function of the form

$$y(x) = c_1 y_1(x) + c_2 y_2(x) \quad (4)$$

will also be a solution of (3).

The Completeness Theorem

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If $y_1(x)$ and $y_2(x)$ are two solutions of

$$y'' + p(x)y' + q(x)y = 0 \quad (3)$$

such that

$$0 \neq W[y_1, y_2](x) \equiv y_1(x)y_2'(x) - y_1'(x)y_2(x) \quad (5)$$

*Then **every solution** of (3) can be written as*

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Solutions y_1, y_2 satisfying (5) are called a **fundamental set of solutions** (or **independent solutions**) of (3).

Geometric Interpretation of the Wronskian Condition

Digression: Independent Vectors in the Plane

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Two non-zero vectors $\mathbf{A}, \mathbf{B} \in \mathbb{R}^2$ are said to be **independent** if

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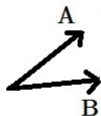
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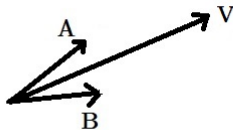
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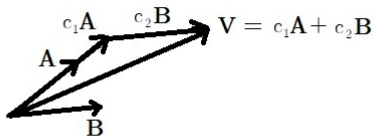
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Lemma

If $y_1(x)$ and $y_2(x)$ fail to satisfy the Wronskian condition, then

$$y_2(x) = \lambda y_1(x)$$

for some constant λ .

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I'll now show you how to find the general solution of (1) starting with just a single solution of (1).

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Thus, any solution we construct by multiplying our given solution $y_1(x)$ by a non-constant function $v(x)$ will give us another linearly independent solution.

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$$\begin{aligned} 0 &= \frac{d^2}{dx^2} (vy_1) + p(x) \frac{d}{dx} (vy_1) + q(vy_1) \\ &= v''y_1 + 2v'y_1' + vy_1'' + p(x)v'y_1 + p(x)vy_1' + qvy_1 \end{aligned}$$

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Note that this is a first order linear ODE for $v'(x)$.

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$$u(x) = \frac{C}{(y_1(x))^2} \exp \left[- \int^x p(t) dt \right] .$$

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$$\begin{aligned} v(x) &= \int^x u(t) dt + D \\ &= \int^x \left[\frac{C}{(y_1(t))^2} \exp \left[- \int^t p(t') dt' \right] \right] + D \end{aligned}$$

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Theorem (Reduction of Order)

If $y_1(x)$ is a solution of

$$y'' + p(x)y' + q(x)y = 0 \quad (1)$$

then a 2nd independent solution $y_2(x)$ can be calculated via the formula

$$y_2(x) = y_1(x) \int^x \frac{1}{(y_1(s))^2} \exp \left[- \int^s p(t) dt \right] ds$$

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Once y_2 has been calculated, the general solution to (1) can be written

$$y(x) = c_1 y_1(x) + c_2 y_2(x)$$

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In the last line, the constant factor of $-\frac{1}{3}$ has been “absorbed” into the arbitrary constant c_2 (for the sake of tidyness).

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We will therefore look for solutions of (9) having the form (10).

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We'll resolve these two issues in the next lecture.

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Note that

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