Math 3013 Linear Algebra Solutions to Final Exam May 4, 2022

- 1. Complete the following definitions
- (a) (5 pts) A subspace of a vector space V is ...
 - a subset W of V such that
 - (i) whenever $\lambda \in \mathbb{R}$, $\mathbf{w} \in W$, $(\lambda \mathbf{w}) \in W$
 - (ii) whenever $\mathbf{w}_1, \mathbf{w}_2 \in W$, $(\mathbf{w}_1 + \mathbf{w}_2) \in W$
- (b) (5 pts) A **basis** for a subspace W of a vector space V is ...
 - a set of vectors $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ such that
 - (i) $W = span(\mathbf{v}_1, \dots, \mathbf{v}_k)$
 - (ii) If $\mathbf{w} = c_1 \mathbf{v}_1 + \dots + c_k \mathbf{v}_k$, then coefficients c_1, \dots, c_k are unique.
- (c) (5 pts) A set of vectors $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ is a **linearly independent** set of vectors if ...
 - the only solution of $x_1\mathbf{v}_1 + \cdots + x_k\mathbf{v}_k = \mathbf{0}$ is $x_1 = 0, \dots, x_k = 0$.
- (d) (5 pts) A linear transformation between two vector spaces V and W is ...
 - A linear transformation between two vector space V and W is a function $T: V \to W$ such that
 - (i) $T(\lambda \mathbf{v}) = \lambda T(\mathbf{v})$ for all $\lambda \in \mathbb{R}$ and all $\mathbf{v} \in V$
 - (ii) $T(\mathbf{v}_1 + \mathbf{v}_2) = T(\mathbf{v}_1) + T(\mathbf{v}_2)$ for all $\mathbf{v}_1, \mathbf{v}_2 \in V$
- 2. Suppose each of the following augmented matrices is a Row Echelon Form of the augmented matrix of a linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$. Describe the original system (i.e., how many equations in how many unknowns) and describe the solution space of the corresponding linear system. (Determine if there are solutions; and, if there are solutions, how many free parameters are needed to describe the general solution.)
- (a) (5 pts) $\begin{bmatrix} 0 & -1 & 0 & 1 & 2 & | & 1 \\ 0 & 0 & 2 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & 2 & 1 & | & 0 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$: There are solutions. The coefficient matrix side of

augmented matrix in REF has 2 columns without pivots, so there will be 2 free parameters in the general solution.

(b) (5 pts) $\begin{bmatrix} 1 & 0 & 4 & 2 & 1 \\ 0 & 2 & 0 & 3 & 2 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$: There are no solutions, as the equation corresponding to

the second to last row is 0 = 1, a mathematical contradiction.

(c) (5 pts) $\begin{bmatrix} 1 & 0 & 2 & | & 1 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$: There is a solution. Since there are no columns without

pivots on the coefficient matrix side of the augmented matrix, there are no free parameters in the general solution (in other words, there is a unique solution).

3. (10 pts) Solve the following linear system, expressing the solution set as a hyperplane.

$$x_1 - x_2 + x_4 = 1$$
$$x_1 + x_2 + x_4 = 1$$
$$x_1 + x_4 = 1$$

• First, we row reduce the augmented matrix for the system to Reduced Row Echelon Form

$$[\mathbf{A}|\mathbf{b}] = \begin{bmatrix} 1 & -1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 1 \end{bmatrix} \quad \underset{\mathbf{row \ reduction}}{\underline{\mathbf{row \ reduction}}} \quad \begin{bmatrix} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = RREF\left([\mathbf{A}|\mathbf{b}]\right)$$

Then, we covert back to equations noting that x_3 and x_4 will be free variables in the solution (RREF has no pivots in columns 3 and 4).

$$\begin{vmatrix} x_1 + x_4 = 1 \\ x_2 = 0 \\ 0 = 0 \end{vmatrix} \Rightarrow \begin{cases} x_1 = 1 - x_4 \\ x_2 = 0 \end{cases}$$

Finally, we write down the form of a solution vector

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 - x_4 \\ 0 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

which displays the solution set as a 2-dimensional hyperplane.

4. (10 pts) Compute the inverse of
$$\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -2 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

$$[\mathbf{A} \mid \mathbf{I}] = \begin{bmatrix} 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & -2 & 0 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix} \quad \underbrace{R_1 \longleftrightarrow R_2}_{\mathbf{A} \leftarrow \mathbf{A} \leftarrow \mathbf{A}} \quad \begin{bmatrix} 1 & -2 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix}$$

and so

$$\mathbf{A}^{-1} = \left[\begin{array}{rrr} 2 & 1 & 0 \\ 1 & 0 & 0 \\ -2 & 0 & 1 \end{array} \right]$$

5. (10 pts) Let $W = \{[x, y] \in \mathbb{R}^2 \mid x + 2y = 3\}$. Prove or disprove that W is a subspace of \mathbb{R}^2 .

• Consider $\mathbf{w} = [1, 1]$. This vector is in W since (1) + (2)(1) = 3. Now consider the scalar multiple of \mathbf{w} by the number 0.

$$(0)$$
 w = $[0, 0] \notin W$ since $(1)(0) + (2)(0) = 0 \neq 3$

Thus, W is not closed under scalar multiplication, and so W is not a subspace.

- 6. Consider the vectors $\{[1,1,1,1],[1,2,-1,1],[2,3,0,2],[3,4,1,3]\} \in \mathbb{R}^4$
- (a) (10 pts) Determine if these vectors are linearly independent.
 - We'll answer this question by row reducing the associated matrix formed by using the given vectors as rows

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & -1 & 1 \\ 2 & 3 & 0 & 2 \\ 3 & 4 & 1 & 3 \end{bmatrix} \xrightarrow{\text{row reduction}} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since there is a zero row at the bottom of the matrix in RREF, the original row vectors could have been linearly independent. Thus, the vectors are not linearly independent.

- (b) (5 pts) What is the dimension of the subspace generated by these vectors (i.e. the subspace spanned by these vectors)?
 - The subspace generated by the original four vectors coincides with the row space of the matrix **A**. We see that there are two non-zero rows in $RREF(\mathbf{A})$, hence, $RowSp(\mathbf{A}) = span([1,1,1,1],[1,2,-1,1],[2,3,0,2],[3,4,1,3])$ is 2-dimensional.
- 7. Consider the following linear transformation: $T: \mathbb{R}^3 \to \mathbb{R}^2 : T([x_1, x_2.x_3]) = [x_2 x_1, x_1 x_2].$ (a) (10 pts) Find a matrix that represents T.
 - $\mathbf{A}_{T} = \left[\begin{array}{ccc} \uparrow & \uparrow & \uparrow \\ T\left([1,0,0]\right) & T\left([0,1,0]\right) & T\left([0,0,1]\right) \\ \downarrow & \downarrow & \downarrow \end{array} \right] = \left[\begin{array}{ccc} -1 & 1 & 0 \\ 1 & -1 & 0 \end{array} \right]$
- (b) (10 pts) Find a basis for the kernel of T (i.e. the set of vectors \mathbf{x} such that $T(\mathbf{x}) = \mathbf{0}$).

$$Ker(T) = NullSp(\mathbf{A}_T)$$

$$= NullSp\left(\begin{bmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix}\right)$$

$$= NullSp\left(\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right)$$

Converting back to equations

$$\mathbf{x} \in NullSp\left(\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \right) \Rightarrow \begin{cases} x_1 - x_2 = 0 \\ 0 = 0 \end{cases}$$

$$\Rightarrow \mathbf{x} = \begin{bmatrix} x_2 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

and so

basis for
$$Ker(T) = \left\{ \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}$$

8. (a) (10 pts) Find the eigenvalues and the eigenvectors of the following matrix:
$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

• We have

$$p_{\mathbf{A}}(\lambda) = \det(\mathbf{A} - \lambda \mathbf{I}) = \det\left(\begin{bmatrix} 2 - \lambda & 1 & 0 \\ 0 & 0 - \lambda & 1 \\ 0 & 0 & 2 - \lambda \end{bmatrix}\right) = (2 - \lambda)^2 (-\lambda)$$

So the eigenvalues of **A** are 2 and 0. Since we have two factors of $(2 - \lambda)$ in $p_{\mathbf{A}}(\lambda)$ the eigenvalue $\lambda = 2$ has algebraic multiplicity 2. Since we have only one factor of $(0-\lambda)$ in $p_{\mathbf{A}}(\lambda)$, the eigenvalue $\lambda=0$ has algebraic multiplicity 1.

2-eigenspace $E_2 = NullSp(\mathbf{A} - (2)\mathbf{I}) = NullSp\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \right) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

$$= span\left(\left[\begin{array}{c} 1\\0\\0\end{array}\right]\right)$$

Since the 2-eigenspace of A has only one basis vector, the geometric multiplicity of the eigenvalue 2 is 1.

0-eigenspace

$$E_0 = NullSp\left(\mathbf{A} - (0)\mathbf{I}\right) = NullSp\left(\begin{bmatrix} 2 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 2 \end{bmatrix}\right) = NullSp\left(\begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}\right)$$
$$= span\left(\begin{bmatrix} -\frac{1}{2} \\ 1 \\ 0 \end{bmatrix}\right)$$

Since the 0-eigenspace of A has only one basis vector, the geometric multiplicity of the eigenvalue 0 is 1.

(b) (5 pts) What are the algebraic multiplicities and geometric multiplicities of the eigenvalues of A?

• We have

eigenvalue basis for eigenspace alg. mult. geom. mult.

$$\left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix} \right\} \qquad \qquad 2 \qquad \qquad 1 \\
 0 \qquad \qquad \left\{ \begin{bmatrix} -\frac{1}{2}\\1\\0 \end{bmatrix} \right\} \qquad \qquad 1 \qquad \qquad 1$$

- (c) (5 pts) Is this matrix diagonalizable?
 - No. We need 3 linearly independent eigenvectors in order to diagonalize a 3×3 matrix. But we only found two linearly independent eigenvectors; and so A is not diagonalizable.

9. (15 pts) Let **A** be the matrix $\begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$. Find a 2×2 matrix **C** and a diagonal matrix **D** such that $\mathbf{C}^{-1}\mathbf{AC} = \mathbf{D}$.

• First, we need to find the eigenvalues and eigenvectors of **A**.

$$p_{\mathbf{A}}(\lambda) = \det\left(\begin{bmatrix} 3-\lambda & 1\\ 1 & 3-\lambda \end{bmatrix}\right) = (3-\lambda)^2 - 1 = \lambda^2 - 6\lambda + 8 = (\lambda - 2)(\lambda - 4)$$

So the eigenvalues of \mathbf{A} are 2 and 4. Next, we look for the corresponding eigenvectors:

2-eigenspace

$$E_{2} = NullSp\left(\begin{bmatrix} 3-2 & 1 \\ 1 & 3-2 \end{bmatrix}\right) = NullSp\left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}\right)$$
$$= span\left(\begin{bmatrix} -1 \\ 1 \end{bmatrix}\right) \Rightarrow \mathbf{v}_{\lambda=2} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

4-eigenspace

$$E_{4} = NullSp\left(\begin{bmatrix} 3-4 & 1 \\ 1 & 3-4 \end{bmatrix}\right) = NullSp\left(\begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}\right)$$
$$= span\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) \Rightarrow \mathbf{v}_{\lambda=4} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

We use the eigenvalues of A to construct the diagonal matrix D and then use the corresponding eigenvectors as the columns of the matrix C. Thus,

$$\mathbf{D} = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix} \qquad , \qquad \mathbf{C} = \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix}$$

- 10. Let $W = span([1, 1, 1], [0, 1, 1]) \subset \mathbb{R}^3$.
- (a) (7 pts) Find the orthogonal complement $W_{\perp} = \{ \mathbf{x} \in \mathbb{R}^3 \mid \mathbf{x} \cdot \mathbf{w} = 0 \text{ for all } \mathbf{x} \in W \}$ of W in \mathbb{R}^3 .
 - Let $\mathbf{b}_1 = [1, 1, 1]$, $\mathbf{b}_2 = [0, 1, 1]$. Every vector in W_{\perp} must perpendicular to both of these basis vectors.

$$\begin{vmatrix}
\mathbf{b}_1 \cdot \mathbf{x} = 0 \\
\mathbf{b}_2 \cdot \mathbf{x} = 0
\end{vmatrix} \Rightarrow \begin{bmatrix}
\leftarrow & \mathbf{b}_1 & \rightarrow \\
\leftarrow & \mathbf{b}_2 & \rightarrow
\end{bmatrix} \mathbf{x} = \mathbf{0}$$

$$\Rightarrow W_{\perp} = NullSp\left(\left[\begin{array}{cc} \leftarrow & \mathbf{b}_{1} & \rightarrow \\ \leftarrow & \mathbf{b}_{2} & \rightarrow \end{array} \right]\right) = NullSp\left(\left[\begin{array}{cc} 1 & 1 & 1 \\ 0 & 1 & 1 \end{array} \right]\right) = NullSp\left(\left[\begin{array}{cc} 1 & 0 & 0 \\ 0 & 1 & 1 \end{array} \right]\right)$$

= solution set of
$$\left\{ \begin{array}{c} x_1 = 0 \\ x_2 + x_3 = 0 \end{array} \right\} = x_3 \left[\begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right]$$

And so

$$W_{\perp} = span\left(\left[\begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right] \right)$$

- (b) (8 pts) Let $\mathbf{v} = [1, -2, 0]$, find the orthogonal decomposition $\mathbf{v} = \mathbf{v}_W + \mathbf{v}_{\perp}$; $\mathbf{v}_W \in W$, $\mathbf{v}_{\perp} \in W_{\perp}$, of \mathbf{v} with respect to W.
 - Combining the basis for W with the basis for W_{\perp} , we have the following basis for \mathbb{R}^3

$$B = \{[1, 1, 1], [0, 1, 1], [0, -1, 1]\}$$

We'll now find suitable coefficients, c_1, c_2, c_3 so that

$$c_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$$

To solve this linear system, we row reduce the corresponding augmented matrix to RREF:

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 1 & 1 & -1 & -2 \\ 1 & 1 & 1 & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

So we must have

$$c_1 = 1$$
 , $c_2 = -2$, $c_3 = 1$

and so

$$\mathbf{v} = (1) \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + (-2) \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + (1) \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$
$$= \mathbf{v}_W + \mathbf{v}_\perp$$

where

$$\mathbf{v}_{W} = (1) \begin{bmatrix} 1\\1\\1 \end{bmatrix} + (-2) \begin{bmatrix} 0\\1\\1 \end{bmatrix} = \begin{bmatrix} 1\\-1\\-1 \end{bmatrix} \in W$$

$$\mathbf{v}_{\perp} = (1) \begin{bmatrix} 0\\-1\\1 \end{bmatrix} = \begin{bmatrix} 0\\-1\\1 \end{bmatrix} \in W_{\perp}$$