

Math 3013 Linear Algebra  
Solutions to Final Exam  
10:00am - 11:50am

1. Complete the following definitions

(a) (5 pts) A **subspace** of a vector space  $V$  is ...

- a subset  $W$  of  $V$  such that
  - (i) whenever  $\lambda \in \mathbb{R}$ ,  $\mathbf{w} \in W$ ,  $(\lambda \mathbf{w}) \in W$
  - (ii) whenever  $\mathbf{w}_1, \mathbf{w}_2 \in W$ ,  $(\mathbf{w}_1 + \mathbf{w}_2) \in W$

(b) (5 pts) A **basis** for a subspace  $W$  of a vector space  $V$  is ...

- a set of vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  such that
  - (i)  $W = \text{span}(\mathbf{v}_1, \dots, \mathbf{v}_k)$
  - (ii) If  $\mathbf{w} = c_1 \mathbf{v}_1 + \dots + c_k \mathbf{v}_k$ , then coefficients  $c_1, \dots, c_k$  are unique.

(c) (5 pts) A set of vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  is a **linearly independent** set of vectors if ...

- the only solution of  $x_1 \mathbf{v}_1 + \dots + x_k \mathbf{v}_k = \mathbf{0}$  is  $x_1 = 0, \dots, x_k = 0$ .

(d) (5 pts) A **linear transformation** between two vector spaces  $V$  and  $W$  is ...

- A linear transformation between two vector space  $V$  and  $W$  is a function  $T : V \rightarrow W$  such that
  - (i)  $T(\lambda \mathbf{v}) = \lambda T(\mathbf{v})$  for all  $\lambda \in \mathbb{R}$  and all  $\mathbf{v} \in V$
  - (ii)  $T(\mathbf{v}_1 + \mathbf{v}_2) = T(\mathbf{v}_1) + T(\mathbf{v}_2)$  for all  $\mathbf{v}_1, \mathbf{v}_2 \in V$

2. For each of the following augmented matrices, describe the solution space of the corresponding linear system. (Determine if there are solutions; and, if there are solutions, how many free parameters are needed to describe the general solution.)

(a) (5 pts) 
$$\left[ \begin{array}{ccccc|c} 0 & -1 & 0 & 1 & 2 & 1 \\ 0 & 0 & 2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

- There are solutions. The coefficient matrix side of augmented matrix in REF has 2 columns without pivots, so there will be 2 free parameters in the general solution.

(b) (5 pts) 
$$\left[ \begin{array}{cccc|c} 1 & 0 & 4 & 2 & 1 \\ 0 & 2 & 0 & 3 & 2 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

- There are no solutions, as the equation corresponding to the second to last row is  $0 = 1$ , a mathematical contradiction.

(c) (5 pts) 
$$\left[ \begin{array}{ccc|c} 1 & 0 & 2 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

- There is a solution. Since there are no columns without pivots on the coefficient matrix side of the augmented matrix, there are no free parameters in the general solution (in other words, there is a unique solution).

3. (10 pts) Compute the inverse of  $\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -2 & 0 \\ 0 & 2 & 1 \end{bmatrix}$

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$$\begin{aligned}
 [\mathbf{A} \mid \mathbf{I}] &= \left[ \begin{array}{ccc|ccc} 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & -2 & 0 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_2} \left[ \begin{array}{ccc|ccc} 1 & -2 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{array} \right] \\
 &\xrightarrow{R_3 \rightarrow R_3 - 2R_2} \left[ \begin{array}{ccc|ccc} 1 & -2 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -2 & 0 & 1 \end{array} \right] \\
 &\xrightarrow{R_1 \rightarrow R_1 + 2R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 2 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -2 & 0 & 1 \end{array} \right] = [\mathbf{I} \mid \mathbf{A}^{-1}]
 \end{aligned}$$

and so

$$\mathbf{A}^{-1} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 0 & 0 \\ -2 & 0 & 1 \end{bmatrix}$$

4. (10 pts) Let  $W = \{[x, y] \in \mathbb{R}^2 \mid x + 2y = 3\}$ . Prove or disprove that  $W$  is a subspace of  $\mathbb{R}^2$ .

- Consider  $\mathbf{w} = [1, 1]$ . This vector is in  $W$  since  $(1) + (2)(1) = 3$ . Now consider the scalar multiple of  $\mathbf{w}$  by the number 0.

$$(0)\mathbf{w} = [0, 0] \notin W \text{ since } (1)(0) + (2)(0) = 0 \neq 3$$

Thus,  $W$  is not closed under scalar multiplication, and so  $W$  is not a subspace.

5. Consider the vectors  $\{[1, 1, 1, 1], [1, 2, -1, 1], [2, 3, 0, 2], [3, 4, 1, 3]\} \in \mathbb{R}^4$

(a) (10 pts) Determine if these vectors are linearly independent.

- We'll answer this question by row reducing the associated matrix formed by using the given vectors as rows

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & -1 & 1 \\ 2 & 3 & 0 & 2 \\ 3 & 4 & 1 & 3 \end{bmatrix} \xrightarrow{\text{row reduction}} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since there is a zero row at the bottom of the matrix in RREF, the original row vectors could have been linearly independent. Thus, **the vectors are not linearly independent.**

(b) (5 pts) What is the dimension of the subspace generated by these vectors (i.e. the subspace spanned by these vectors)?

- The subspace generated by the original four vectors coincides with the row space of the matrix  $\mathbf{A}$ . We see that there are two non-zero rows in  $RREF(\mathbf{A})$ , hence,  $RowSp(\mathbf{A}) = span([1, 1, 1, 1], [1, 2, -1, 1], [2, 3, 0, 2], [3, 4, 1, 3])$  is 2-dimensional.

6. Consider the following linear transformation:  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2 : T([x_1, x_2, x_3]) = [x_2 - x_1, x_1 - x_2]$ .

(a) (10 pts) Find a matrix that represents  $T$ .

$$\mathbf{A}_T = \begin{bmatrix} \uparrow & \uparrow & \uparrow \\ T([1, 0, 0]) & T([0, 1, 0]) & T([0, 0, 1]) \\ \downarrow & \downarrow & \downarrow \end{bmatrix} = \begin{bmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix}$$

(b) (10 pts) Find a basis for the kernel of  $T$  (i.e. the set of vectors  $\mathbf{x}$  such that  $T(\mathbf{x}) = \mathbf{0}$ ).

$$\begin{aligned} Ker(T) &= NullSp(\mathbf{A}_T) \\ &= NullSp\left(\begin{bmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix}\right) \\ &= NullSp\left(\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) \end{aligned}$$

Converting back to equations

$$\begin{aligned} \mathbf{x} \in NullSp\left(\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) &\Rightarrow \begin{cases} x_1 - x_2 = 0 \\ 0 = 0 \end{cases} \\ \Rightarrow \mathbf{x} = \begin{bmatrix} x_2 \\ x_2 \\ x_3 \end{bmatrix} &= x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

and so

$$\text{basis for } Ker(T) = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

7. (a) (10 pts) Find the eigenvalues and the eigenvectors of the following matrix :  $\mathbf{A} = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 2 \end{bmatrix}$

- We have

$$p_{\mathbf{A}}(\lambda) = \det(\mathbf{A} - \lambda \mathbf{I}) = \det \left( \begin{bmatrix} 2-\lambda & 1 & 0 \\ 0 & 0-\lambda & 1 \\ 0 & 0 & 2-\lambda \end{bmatrix} \right) = (2-\lambda)^2(-\lambda)$$

So the eigenvalues of  $\mathbf{A}$  are 2 and 0. Since we have two factors of  $(2-\lambda)$  in  $p_{\mathbf{A}}(\lambda)$  the eigenvalue  $\lambda = 2$  has algebraic multiplicity 2. Since we have only one factor of  $(0-\lambda)$  in  $p_{\mathbf{A}}(\lambda)$ , the eigenvalue  $\lambda = 0$  has algebraic multiplicity 1.

2-eigenspace

$$\begin{aligned} E_2 &= \text{NullSp}(\mathbf{A} - (2)\mathbf{I}) = \text{NullSp} \left( \begin{bmatrix} 0 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \right) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \\ &= \text{span} \left( \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) \end{aligned}$$

Since the 2-eigenspace of  $\mathbf{A}$  has only one basis vector, the geometric multiplicity of the eigenvalue 2 is 1.

0-eigenspace

$$\begin{aligned} E_0 &= \text{NullSp}(\mathbf{A} - (0)\mathbf{I}) = \text{NullSp} \left( \begin{bmatrix} 2 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 2 \end{bmatrix} \right) = \text{NullSp} \left( \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \right) \\ &= \text{span} \left( \begin{bmatrix} -\frac{1}{2} \\ 1 \\ 0 \end{bmatrix} \right) \end{aligned}$$

Since the 0-eigenspace of  $\mathbf{A}$  has only one basis vector, the geometric multiplicity of the eigenvalue 0 is 1.

(b) (5 pts) What are the algebraic multiplicities and geometric multiplicities of the eigenvalues of  $\mathbf{A}$ ?

- We have

eigenvalue	basis for eigenspace	alg. mult.	geom. mult.
2	$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$	2	1
0	$\left\{ \begin{bmatrix} -\frac{1}{2} \\ 1 \\ 0 \end{bmatrix} \right\}$	1	1

(c) (5 pts) Is this matrix diagonalizable?

- No. We need 3 linearly independent eigenvectors in order to diagonalize a  $3 \times 3$  matrix. But we only found two linearly independent eigenvectors; and so  $\mathbf{A}$  is not diagonalizable.

8. (15 pts) Let  $\mathbf{A}$  be the matrix  $\begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$ . Find a  $2 \times 2$  matrix  $\mathbf{C}$  and a diagonal matrix  $\mathbf{D}$  such that  $\mathbf{C}^{-1}\mathbf{A}\mathbf{C} = \mathbf{D}$ .

- First, we need to find the eigenvalues and eigenvectors of  $\mathbf{A}$ .

$$p_{\mathbf{A}}(\lambda) = \det \left( \begin{bmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{bmatrix} \right) = (3-\lambda)^2 - 1 = \lambda^2 - 6\lambda + 8 = (\lambda - 2)(\lambda - 4)$$

So the eigenvalues of  $\mathbf{A}$  are 2 and 4. Next, we look for the corresponding eigenvectors:

2-eigenspace

$$\begin{aligned} E_2 &= \text{NullSp} \left( \begin{bmatrix} 3-2 & 1 \\ 1 & 3-2 \end{bmatrix} \right) = \text{NullSp} \left( \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \right) \\ &= \text{span} \left( \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right) \Rightarrow \mathbf{v}_{\lambda=2} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \end{aligned}$$

4-eigenspace

$$\begin{aligned} E_4 &= \text{NullSp} \left( \begin{bmatrix} 3-4 & 1 \\ 1 & 3-4 \end{bmatrix} \right) = \text{NullSp} \left( \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \right) \\ &= \text{span} \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) \Rightarrow \mathbf{v}_{\lambda=4} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{aligned}$$

We use the eigenvalues of  $\mathbf{A}$  to construct the diagonal matrix  $\mathbf{D}$  and then use the corresponding eigenvectors as the columns of the matrix  $\mathbf{C}$ . Thus,

$$\mathbf{D} = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix}, \quad \mathbf{C} = \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix}$$

9. Let  $W = \text{span}([1, 1, 1], [0, 1, 1]) \subset \mathbb{R}^3$ .

(a) (7 pts) Find the orthogonal complement  $W_\perp = \{\mathbf{x} \in \mathbb{R}^3 \mid \mathbf{x} \cdot \mathbf{w} = 0 \text{ for all } \mathbf{x} \in W\}$  of  $W$  in  $\mathbb{R}^3$ .

- Let  $\mathbf{b}_1 = [1, 1, 1]$ ,  $\mathbf{b}_2 = [0, 1, 1]$ . Every vector in  $W_\perp$  must be perpendicular to both of these basis vectors.

$$\left. \begin{array}{l} \mathbf{b}_1 \cdot \mathbf{x} = 0 \\ \mathbf{b}_2 \cdot \mathbf{x} = 0 \end{array} \right\} \Rightarrow \left[ \begin{array}{ccc} \leftarrow & \mathbf{b}_1 & \rightarrow \\ \leftarrow & \mathbf{b}_2 & \rightarrow \end{array} \right] \mathbf{x} = \mathbf{0}$$

$$\begin{aligned} \Rightarrow W_\perp &= \text{NullSp} \left( \left[ \begin{array}{ccc} \leftarrow & \mathbf{b}_1 & \rightarrow \\ \leftarrow & \mathbf{b}_2 & \rightarrow \end{array} \right] \right) = \text{NullSp} \left( \left[ \begin{array}{ccc} 1 & 1 & 1 \\ 0 & 1 & 1 \end{array} \right] \right) = \text{NullSp} \left( \left[ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 1 \end{array} \right] \right) \\ &= \text{solution set of } \left\{ \begin{array}{l} x_1 = 0 \\ x_2 + x_3 = 0 \end{array} \right\} = x_3 \left[ \begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right] \end{aligned}$$

And so

$$W_\perp = \text{span} \left( \left[ \begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right] \right)$$

(b) (8 pts) Let  $\mathbf{v} = [1, -2, 0]$ , find the orthogonal decomposition  $\mathbf{v} = \mathbf{v}_W + \mathbf{v}_\perp$ ;  $\mathbf{v}_W \in W$ ,  $\mathbf{v}_\perp \in W_\perp$ , of  $\mathbf{v}$  with respect to  $W$ .

- Combining the basis for  $W$  with the basis for  $W_\perp$ , we have the following basis for  $\mathbb{R}^3$

$$B = \{[1, 1, 1], [0, 1, 1], [0, -1, 1]\}$$

We'll now find suitable coefficients,  $c_1, c_2, c_3$  so that

$$c_1 \left[ \begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right] + c_2 \left[ \begin{array}{c} 0 \\ 1 \\ 1 \end{array} \right] + c_3 \left[ \begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right] = \left[ \begin{array}{c} 1 \\ -2 \\ 0 \end{array} \right]$$

To solve this linear system, we row reduce the corresponding augmented matrix to RREF:

$$\left[ \begin{array}{cccc} 1 & 0 & 0 & 1 \\ 1 & 1 & -1 & -2 \\ 1 & 1 & 1 & 0 \end{array} \right] \longrightarrow \left[ \begin{array}{cccc} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 1 \end{array} \right]$$

So we must have

$$c_1 = 1, \quad c_2 = -2, \quad c_3 = 1$$

and so

$$\begin{aligned} \mathbf{v} &= (1) \left[ \begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right] + (-2) \left[ \begin{array}{c} 0 \\ 1 \\ 1 \end{array} \right] + (1) \left[ \begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right] \\ &= \mathbf{v}_W + \mathbf{v}_\perp \end{aligned}$$

where

$$\begin{aligned}\mathbf{v}_W &= (1) \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + (-2) \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} \in W \\ \mathbf{v}_\perp &= (1) \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \in W_\perp\end{aligned}$$

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10. (10 pts) Find an orthonormal basis for the subspace  $W$  generated by the vectors  $\mathbf{v}_1 = [1, -1, 1]$  and  $\mathbf{v}_2 = [1, 0, 2]$ .

- First, we'll construct an orthogonal basis  $\{\mathbf{o}_1, \mathbf{o}_2\}$  for  $W$ . We set

$$\mathbf{o}_1 = \mathbf{v}_1 = [1, -1, 1]$$

The second orthogonal basis vector is formed by removing from  $\mathbf{v}_2$ , the component that runs parallel to  $\mathbf{o}_1 = \mathbf{v}_1$ :

$$\mathbf{o}_2 = \mathbf{v}_2 - \frac{\mathbf{o}_1 \cdot \mathbf{v}_2}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 = [1, 0, 2] - \frac{(1 + 0 + 2)}{(1 + 1 + 1)} [1, -1, 1] = \begin{bmatrix} 0 & 1 & 1 \end{bmatrix}$$

To get an orthonormal basis  $\{\mathbf{n}_1, \mathbf{n}_2\}$  from  $\{\mathbf{o}_1, \mathbf{o}_2\}$  we just have to divide  $\mathbf{o}_1$  and  $\mathbf{o}_2$  by their lengths, so that we get orthogonal basis vectors of unit length:

$$\begin{aligned}\mathbf{n}_1 &= \frac{\mathbf{o}_1}{\sqrt{\mathbf{o}_1 \cdot \mathbf{o}_1}} = \frac{1}{\sqrt{3}} [1, -1, 1] = \left[ \frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right] \\ \mathbf{n}_2 &= \frac{\mathbf{o}_2}{\sqrt{\mathbf{o}_2 \cdot \mathbf{o}_2}} = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 & 1 \end{bmatrix} = \left[ 0, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right]\end{aligned}$$