# Lecture 35 : Orthogonal Decompositions: Examples

Math 3013 Oklahoma State University

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- 1. Orthogonal Decompositions (Summary)
- 2. Examples

1: Orthogonal Decompositions: Summary

1. The Orthogonal Decomposition of a Vector  ${\bf a}$  with respect to a Vector  ${\bf b}$ 



 $\mathbf{a} = \mathbf{a}_{\mathbf{b}} + \mathbf{a}_{\perp}$ 

where

# Orthogonal Decompositions: Summary Cont'd

2. The Orthogonal Decomposition of a Vector **v** with respect to a subspace  $W \subseteq \mathbb{R}^n$ 



$$\mathbf{v} = \mathbf{v}_W + \mathbf{v}_\perp$$

To identify the components  $\mathbf{v}_W$  and  $\mathbf{v}_{\perp}$ , we first decompose  $\mathbb{R}^n$  into two perpendicular subspaces W and  $W_{\perp}$ .

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#### Determining $\mathbf{v}_W$ and $\mathbf{v}_\perp$

Find a basis B<sub>W</sub> = {b<sub>1</sub>,..., b<sub>k</sub>} for W
Define W<sub>⊥</sub> = {v ∈ ℝ<sup>n</sup> | v ⋅ w = 0 for all w ∈ W}
Lemma: W<sub>⊥</sub> = NullSp   

$$\begin{pmatrix} \leftarrow b_1 \rightarrow \\ \vdots \\ \leftarrow b_k \rightarrow \end{pmatrix}$$

Find a basis B<sub>W⊥</sub> = {b<sub>k+1</sub>,..., b<sub>n</sub>} for W⊥ by solving the homogeneous linear system

$$\begin{bmatrix} \leftarrow & \mathbf{b}_1 & \rightarrow \\ & \vdots & \\ \leftarrow & \mathbf{b}_k & - \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

▶  $B = {\mathbf{b}_1, \dots, \mathbf{b}_k, \mathbf{b}_{k+1}, \dots, \mathbf{b}_n}$  is then a basis for  $\mathbb{R}^n$ .

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Find the coordinate vector v<sub>B</sub> of v ∈ ℝ<sup>n</sup> with respect to the basis B

$$\mathbf{v} = c_1 \mathbf{b}_1 + \cdots + c_n \mathbf{b}_n \quad \Longleftrightarrow \quad \mathbf{v}_B = [c_1, \dots, c_n]$$

by row reducing the corresponding augmented matrix

$$\begin{bmatrix} \uparrow & \uparrow & \uparrow \\ \mathbf{b}_1 & \cdots & \mathbf{b}_n & \mathbf{v} \\ \downarrow & \downarrow & \downarrow & \downarrow \end{bmatrix} \longrightarrow \begin{bmatrix} \mathbf{I} \mid \mathbf{v}_B \end{bmatrix}$$

We then have

$$\mathbf{v} = \mathbf{v}_W + \mathbf{v}_\perp$$

where

$$\mathbf{v}_W = c_1 \mathbf{b}_1 + \dots + c_k \mathbf{b}_k$$
$$\mathbf{v}_\perp = c_{k+1} \mathbf{b}_{k+1} + \dots + c_n \mathbf{b}_n$$

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## Example 1

Let  $W = span([1,0,1],[0,1,1]]) \subset \mathbb{R}^3$ . Decompose the vector  $\mathbf{v} = [1,4,-4]$  into its components  $\mathbf{v}_W \in W$  and  $\mathbf{v}_{W_{\perp}} \in W_{\perp}$ .

The two vectors  $\mathbf{b}_1 \equiv [1,0,1]$  and  $\mathbf{b}_2 \equiv [0,1,1]$  are obviously linearly independent and so  $B_W = {\mathbf{b}_1, \mathbf{b}_2}$  is already a basis for W. To get a basis for  $W_{\perp}$ , we compute the null space of

$$\mathbf{A}_{W,B} = \begin{bmatrix} \leftarrow & \mathbf{b}_1 & \rightarrow \\ \leftarrow & \mathbf{b}_2 & \rightarrow \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

This matrix is already in reduced row echelon form and its null space will be the solution set of

$$\begin{array}{c} x_1 + x_3 = 0 \\ x_2 + x_3 = 0 \end{array} \right\} \quad \Longrightarrow \quad \mathbf{x} = x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

 $\implies \quad B_{W_{\perp}} = \{[-1, -1, 1]\} \equiv \{\mathbf{b}_3\}$ 

## Example 1, Cont'd

We now compute the coordinate vector of  $\boldsymbol{v} = [1,4,-4]$  with respect to the basis

$$B = B_W \cup B_{W_\perp} = \{ [1, 0, 1], [0, 1, 1], [-1, -1, 1] \}$$

of  $\mathbb{R}^3$ 

$$\begin{bmatrix} \uparrow & \cdots & \uparrow & | \uparrow \\ \mathbf{b}_1 & \cdots & \mathbf{b}_n & \mathbf{v} \\ \downarrow & \cdots & \downarrow & | \downarrow \end{bmatrix} = \begin{bmatrix} 1 & 0 & -1 & | & 1 \\ 0 & 1 & -1 & | & 4 \\ 1 & 1 & 1 & | & -4 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & | & -2 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & -3 \end{bmatrix}$$

So  $\mathbf{v}_B = [-2, 1, -3]$ . But now

$$\mathbf{v} = (-2) \, \mathbf{b}_1 + (1) \, \mathbf{b}_2 + (-3) \, \mathbf{b}_3$$

and so

$$\mathbf{v}_{W} = (-2) \mathbf{b}_{1} + (1) \mathbf{b}_{2} = [-2, 1, -1]$$
  
$$\mathbf{v}_{W_{\perp}} = (-3) \mathbf{b}_{3} = [3, 3, -3]$$

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## Example 2

Find the projection of the vector  $\mathbf{v} = [1, 2, 1]$  on the solution set of  $x_1 + x_2 + x_3 = 0$ .

Let

$$W = \left\{ [x_1, x_2, x_3] \in \mathbb{R}^3 \mid x_1 + x_2 + x_3 = 0 \right\}$$

Solving the linear equation, we find that

$$W = span\left( \left[ \begin{array}{c} -1\\1\\0 \end{array} \right], \left[ \begin{array}{c} -1\\0\\1 \end{array} \right] \right)$$

and  $\left\{ \left[ -1,1,0\right] ,\left[ -1,0,1\right] \right\}$  is a basis for  $\mathit{W}.$   $\mathit{W}_{\! \perp}$  will then be

$$\begin{aligned} & \textit{NullSp}\left(\left[\begin{array}{rrrr} -1 & 1 & 0 \\ -1 & 0 & 1 \end{array}\right]\right) &= \textit{NullSp}\left(\left[\begin{array}{rrrr} 1 & 0 & -1 \\ 0 & 1 & -1 \end{array}\right]\right) \\ &= \textit{span}\left([1, 1, 1]\right) \end{aligned}$$

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#### Example 2, Cont'd

So

So we have split  $\mathbb{R}^n$  into two subspaces

$$W = span([-1, 1, 0], [-1, 0, 1])$$
,  $W_{\perp} = span([1, 1, 1])$ 

and  $B = \{[-1, 1, 0], [-1, 0, 1], [1, 1, 1]\}$  is a basis for  $\mathbb{R}^n$ .

To identify  $\mathbf{v}_W$ , the component of the vector  $\mathbf{v}$  that lies in W, we need the first two components of the coordinate vector of  $\mathbf{v}$  with respect to the basis B.

$$\begin{bmatrix} -1 & -1 & 1 & | & 1 \\ 1 & 0 & 1 & | & 2 \\ 0 & 1 & 1 & | & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & | & \frac{2}{3} \\ 0 & 1 & 0 & | & -\frac{1}{3} \\ 0 & 0 & 1 & | & \frac{4}{3} \end{bmatrix}$$
$$\mathbf{v}_{W} = \frac{2}{3} \left[ -1, 1, 0 \right] - \frac{1}{3} \left[ -1, 0, 1 \right] = \left[ -\frac{1}{3}, \frac{2}{3}, \frac{-1}{3} \right]$$

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#### Review: Row Reduction Calculations

Row Echelon Form and Reduced Row Echelon Form

$$R.E.F. \sim \begin{bmatrix} \frac{*}{0} & * & * & * & * & * \\ 0 & 0 & \frac{*}{2} & * & * & * \\ 0 & 0 & 0 & \frac{*}{2} & * & * \\ 0 & 0 & 0 & 0 & \frac{*}{2} & * \end{bmatrix} \quad , \quad R.R.E.F. \sim \begin{bmatrix} \frac{1}{0} & * & 0 & 0 & 0 & * \\ 0 & 0 & \frac{1}{0} & 0 & 0 & * \\ 0 & 0 & 0 & \frac{1}{0} & 0 & * \\ 0 & 0 & 0 & 0 & \frac{1}{1} & * \\ \end{bmatrix}$$

**Elementary Row Operations** 

$$egin{array}{rcl} R_i & \longleftrightarrow & R_j \ R_i & 
ightarrow & \lambda R_i \ R_i & 
ightarrow & R_i + \lambda R_j \end{array}$$

## Applications of Row Reduction

 Solving Linear Systems Ax = b : row reduce [A|b] to its R.R.E.F. Important Special Case:

 $NullSp(\mathbf{A}) =$  solution set of  $\mathbf{A}\mathbf{x} = \mathbf{0}$ 

(2) Finding basis for subspace  $W = span(\mathbf{v}_1, \dots, \mathbf{v}_k)$ : row reduce  $\begin{bmatrix} \leftarrow \mathbf{v}_1 \rightarrow \\ \vdots \\ \leftarrow \mathbf{v}_k \rightarrow \end{bmatrix}$  to R.E.F. and grab non-zero rows

# (3) Finding bases for subspaces attached to matrices: If A" = R.R.E.F.(A)

- (i) basis for  $RowSp(\mathbf{A}) \leftrightarrow nonzero rows of \mathbf{A}''$
- (ii) basis for  $ColSp(\mathbf{A}) \longleftrightarrow$  columns of  $\mathbf{A}$  corresponding to columns of  $\mathbf{A}''$  that contain pivots
- (iii) basis for  $NullSp(\mathbf{A}) \leftrightarrow$  constant vectors that occur in hyperplane expression for the solution set of  $\mathbf{Ax} = \mathbf{0}$

# (4) Finding $\mathbf{A}^{-1}$ : R.R.E.F. ([ $\mathbf{A}$ | $\mathbf{I}$ ]) = [ $\mathbf{I}$ | $\mathbf{A}^{-1}$ ] (if $\mathbf{A}^{-1}$ exists)

(5) If  $T : \mathbb{R}^m \to \mathbb{R}^n$  is a linear transformation

$$\mathbf{A}_{T} = \begin{bmatrix} \uparrow & \uparrow \\ T(\mathbf{e}_{1}) & \cdots & T(\mathbf{e}_{m}) \\ \downarrow & \downarrow \end{bmatrix}$$

$$Range(T) = ColSp(\mathbf{A}_{T})$$

$$Ker(T) = NullSp(\mathbf{A}_{T})$$

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(6) Calculating Determinants: Suppose  $\mathbf{A} \rightarrow \mathbf{A}' = R.E.F.(\mathbf{A})$ 

$$\det (\mathbf{A}) = (-1)^{i} \frac{1}{\lambda_{1} \cdots \lambda_{k}} a'_{11} a'_{22} \cdots a'_{nn}$$

where

$$i = \#$$
 of row interchanges  $R_i \leftrightarrow R_j$  used  
 $\lambda_i =$ scalar factors used via  $R_i \rightarrow \lambda R_i$  type operations  
 $a'_{ii} =$ diagonal entries of the R.E.F. **A**' of **A**

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(7) Finding eigenvectors (i.e., basis vectors for eigenspaces)

$$E_r = NullSp(\mathbf{A} - r\mathbf{I})$$

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